# Heavy Gas Čerenkov Mirror Reflectivity Measurements

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### 1 Introduction

Due to the expensive shipping and service cost for aluminizing the Heavy Gas Čerenkov mirrors at Cern, we are considering a new possible vendor who can provide equivalent service at lower cost and deliver the products in a shorter period of time. In November 2011, two HGC mirrors were selected and sent to  $ECI^1$  to be aluminized for testing purposes. The aluminized mirrors were then sent to Jefferson Lab within two weeks. The University of Regina and Jefferson Lab (Hall C, Detector Group and FEL) are collaborating to construct a permanent setup to measure the real mirror reflectivity between 165-400nm, with the measurement below 190nm are performed under pure  $N_2$  environment. The maximum hosted mirror dimension is  $60 \text{cm} \times 50 \text{cm}$ , with curvature radius of 110cm. The first objective of this setup is to confirm the reflectivity of the ECI's coated mirror surface between 200-400nm wavelength.

We report the completion of the mirror reflectivity setup and the first measurement on the ECI coated HGC mirrors. The HGC mirror bracket has dimension of 60cm×55cm, and curvature radius of 110cm, for more detailed information on the HGC mirrors, please see the prior technical report[1].

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<sup>&</sup>lt;sup>1</sup>Evaporated Coatings Inc. 2365 Maryland Road, Willow Grove, PA 19090

### 2 Methodology

### 2.1 Equipment list

The list of important components used for the setup construction is given below:

- 2 × IRD<sup>2</sup> AXUV-100G photo-diode UV Detectors (#02, #18) with Ceramic Shoulders
- Thorlab MC100 Optical Chopper System with MC1F2 Chopping Blade
- SR530 Lock-in Amplifier
- The McPherson Model 218 Vacuum Ultraviolet (VUV) Monochromator with Holographic 200nm Blaze (1200G/mm) Grating
- 1mW Melles Griot Alignment Laser
- 3 Watt Hamamastu Deuterium UV Light Source
- Deep UV Flipper Mirror: Melles Griots DUVA-PM-5010M-UV
- F1.5 Focusing Lens: Edmund Optics UV Plano-Convex 50mm Dia.x75mm FL Uncoated Lens
- F4 Focusing Lens: Edmund Optics CAF2 PCX50.8 Lens
- 1 × Translation Stage, 1 × Rotation Stage and 8 × Stepper Motors

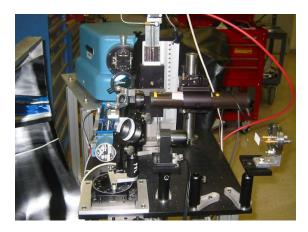
The mirror reflectivity measurements used the HGC mirror #8 and IRD UV detector #02. The HGC mirror is clamped along the left and bottom edges with metal clamps (two along each side). The clamped mirror edges are sandwiched between the rubber gasket to isolate them from the metal pieces.

### 2.2 Setup

The main body of the setup is constructed by three parts as shown in Fig. 1 and 2: the light source box, the monochromator and the detector hutch. In Fig. 1 the hutch was not yet installed

The light box houses the Hamamatsu deuterium lamp and F1.5 focussing lens. The distance between the lamp and the lens is 4cm, and the distance between the lens and the light entering

<sup>&</sup>lt;sup>2</sup>International Radiation Detectors, Inc. Opto Diode Corp. 750 Mitchel Road, Newbury Park, CA 91320



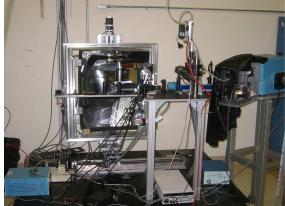


Figure 1: Pictures of the mirror reflectivity setup.

the slit of the monochromator is also 4cm. The monochromator was calibrated and installed with a brand new holographic 200nm blaze (1200G/mm) grating to optimize the performance around 200nm wavelength.

Inside of the detector hutch, the test mirror is clamped onto the hosting bracket and then mounted to the angle adjusting frame. The stepper motors attached to the frame are able to change the pitch and yaw angle with an accuracy of  $0.1^{\circ}$ . The whole frame sits upon a three axis translation stage which allows the source light from the monochromator to reach any spot on the sample mirror.

During the reflectivity measurement, the detector position is fixed at a constant point. This means the sample mirror's position and angle needs to be adjusted to reflect the source light towards the detector. Since the human eye does not respond to MUV or FUV light, an alignment laser is introduced to match the monochromator light path, in order to help guide the mirror adjustment. The laser is installed in perpendicular to the monochromator light path, and a pneumatically controlled stage device will insert a small reflecting mirror to intercept the light path if the laser is needed for alignment Fig. 1

The air will start to block UV light around 190nm, so for the reflectivity measurement at wavelengths below 190nm, an oxygen free environment is required. A high vacuum environment would be ideal, but the cost of the large vacuum chamber is beyond the budget. Instead, a pure  $N_2$  environment is used, where the leak tight requirements for a purged system are much less demanding. All three parts of the setup can be fed with cool  $N_2$  gas separately. The volume of the hutch may need several hours of purging before reaching the condition necessary for reflectivity measurement. The purging process will continue during the data taking period to maintain the low oxygen level and also cool the UV lamp. An oxygen monitor will be placed inside of the hutch to readout

the oxygen level. For the HGC mirror reflectivity measurement, the wavelength range of interest is 190-400nm, therefore the pure  $N_2$  condition is not required.

### 2.3 Methodology and Schematic Diagrams

We performed wavelength scans between 190-400nm at three different modes to compute the final results and the their descriptions are listed as follows:

**No Reflection (NR) Mode:** Light from the monochromator slit was focused by the focusing lens and the image was directly projected onto the detector. The slit-lens distance  $(d_o)$  was 31cm, and the lens-detector distance  $(d_{l-d})$  was 69cm. The wavelength scan at this mode was used as the reference measurement for determination of the flipper mirror reflectivity. Only one measurement was taken.

Flipper Mirror Reflection (FMR) Mode: The  $d_o$  was the same as that for the NR mode. However, the light was then reflected off the Deep Ultra Violet (DUV) flipper mirror and projected onto the detector. The total light path of this mode was equivalent to the NR mode. The flipper mirror was rotated to  $10.75^{\circ}$  according to the rotation stage indicator and the light incidence angle to the flipper mirror was  $47.5^{\circ}$ . Other key parameters are listed in Table 1. The wavelength scans at this mode were used for the reflection measurement to compute the flipper mirror reflectivity, as well as the reference measurement to compute the test mirror reflectivity. A total of 8 measurements of wavelength scan were taken across the 8 hour testing period. Measurement: Flipper Mirror Reflection (FMR) 1 and FMR2 were done immediately after the NR measurement. Measurements Left FMR, Right FMR, Center FMR, Top FMR, Bottom FMR and Corner FMR were performed before the Real Mirror Reflection Measurement at the indicated mirror location. The schematic diagram of this mode is shown in Fig. 2a.

**Real Mirror Reflection (RMR) Mode:** With  $d_o$  reduced to 22.2cm, the flipper mirror was rotated by 95°, where the rotating stage indicator should record 105.75°. The schematic digram of this mode is shown in Fig. 2b. After the focusing lens, the light was first reflected by the flipper mirror towards the test mirror instead of detector, then the test mirror reflected the light towards the detector. The light incidence angles to the flipper mirror and test mirror were 47.5° and 5.5° accordingly. From Table 1, the total light path of this mode was 2 times longer than the NR and FMR mode. The focused spot size is also larger. The wavelength scan of this mode will be used as the reflection measurement to compute the test mirror

reflectivity. There were 6 measurements in total in this mode, and each measurement was performed immediately after the FMR measurement corresponds to the same orientation (Left FMR, Right FMR and so on). The exact position of these labels on the test mirror is shown in Fig. 4b.

The flipper mirror reflectivity is computed as

$$R_{flipper} = \frac{I_{FMR}}{I_{NR}} \tag{1}$$

where  $I_{FMR}$  is the signal strength at arbitrary wavelength in Flipper Mirror Reflection Mode,  $I_{NR}$  is the signal strength at the same arbitrary wavelength in the NR Mode.

The real mirror reflectivity is determined as

$$R = \frac{I_{RMR}}{I_{FMR}} \tag{2}$$

where  $I_{RMR}$  is the signal strength at arbitrary wavelength in RMR Mode,  $I_{FMR}$  is the signal strength at the same arbitrary wavelength in the FMR Mode.

The focal length of a lens is dependent on the incoming light's wavelength. All three modes project a focused image of the source (monochromator) onto the detector at 225nm. The focused image size of each mode is listed in Table 1. The image will be slightly out of focus (blurry) at higher and lower wavelength. The active area of the detector is  $1 \text{cm} \times 1 \text{cm}$  which is sufficient to detect the slightly blurred image.

Table 1 shows the distance between the important components in various different modes.

 $d_o$ : Distance between beam out slit of monochromator to focusing lens.

 $d_{l-f}$ : Distance between focusing lens and flipper mirror.

 $d_{f-d}$ : Distance between flipper mirror and detector.

 $d_{l-d}$ : Distance between focusing lens and detector.

 $d_{f-m}$ : Distance between flipper mirror and real mirror.

 $d_{m-d}$ : Distance between real mirror and detector.

 $d_i$ : Total length of light path from the lens and detector (The sum of  $d_{l-f}$ ,  $d_{f-d}$ ,  $d_{l-d}$ ,  $d_{f-m}$  and  $d_{m-d}$  for each mode).

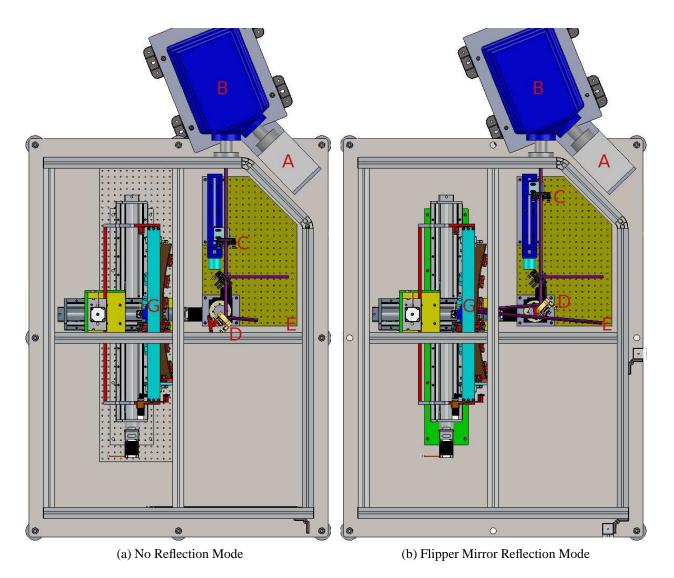


Figure 2: Schematic diagram for different measurement modes. All important components are labelled with a capital letter. A: Light source box; B: Monochromator; C: Focusing lens; D: Flipper Mirror; E: Detector; G: Mirror Holding Frame. Position of the focusing lens (C) and flipper mirror (D) are different between the two modes. <sup>a</sup>

<sup>&</sup>lt;sup>a</sup>Conceptual design of the setup is by Michelle Shinn and Engineering design is by Chris Gould. Image courtesy of Chris Gould.

	No Reflection	Flipper Mirror	Real Mirror
	Mode	Reflection Mode	Reflection Mode
$d_o$	31cm	31cm	22.2cm
$d_{l-f}$	-	42cm	43.3cm
$d_{f-d}$	-	27cm	-
$d_{l-d}$	69cm	-	-
$d_{f-m}$	-	-	34cm
$d_{m-d}$	-	-	60cm
$d_{i}$	69cm	69cm	137.3
A	6mm×5mm	6mm×5mm	$8\text{mm}\times7\text{mm}$
$T_{flipper}$	-	105.75°	10.75°

Table 1: The key parameters for all measurement modes.

A: Focused beam spot at the detector at 225nm wavelength.

 $T_{flipper}$  Flipper mirror angle according to the rotation stage angle indicator.

### 2.4 Detector and Signal Schematic Diagram

For all measurement modes, the continuous light signal was converted to pulsed light signal by the Thorlab MC100 optical chopper before reaching the detector. The chopper had a 2 slot chopping blade operated at a frequency of 14Hz. The chopper generated a reference frequency and it was fed to the reference channel of the lock-in amplifier. The detector generated a pulsed DC differential signal through two connecting points, the two signals were fed into the input channels A and B of the lock-in amplifier. Then the lock-in amplifier would subtract signal B from A, and perform the filtering and amplifying algorithm. The schematic diagram of the signal treatment is shown in Fig. 3.

### 2.5 Lock-in Method and Monochromator Scanning Setting

The lock-in technique is used to detect and measure very small AC signals. A lock-in amplifier can make accurate measurement of small signals even when the signals are obscured by background noise thousands of times larger. Essentially, a lock-in filter is a filter with an arbitrarily narrow bandwidth which is tuned to the frequency of the signal. Such a filter rejects most unwanted noise to allow the signal to be measured.

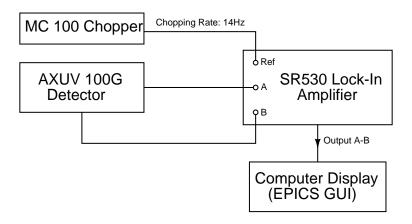


Figure 3

All lock-in measurements share a few basic principles. The technique requires that the experiment be excited at a fixed frequency in a relatively quiet part of the noise spectrum. Then, the lock-in can detect the response from the experiment in a very narrow bandwidth at the excitation frequency.

In this measurement, the SR530 lock-in amplifier was operated in R,  $\theta$  display mode, where R stood for the signal magnitude and  $\theta$  gave the phase between measured signal and the reference. The reference signal was generated by the optical chopper which chopped at the rate of 14Hz. The critical settings for the SR530 were as following:

Signal Filters Bandpass: OUT. ENBW: 1Hz. Notch 1X: OUT. Notch 2X: OUT.

**Reference** Frequency: 14Hz (From the Optical Chopper). Mode: 1f, Triger: POS.

**Sensitivity** 5mV (must make sure the status is not overloading). Dynamic reserve: NORMAL.

**Time Constant** Pre: 3s. Post: none.

**Output** Display: R,  $\Theta$ . Chan1 expand: X1. Chan2 expand: X1. Xoffset: OFF. Yoffset: OFF. Roffset: ON (Baseline signal =  $1.6 \times 10^{-5}$ V).

**Status** ENABLE GRIP. Remote (Reselect the sensitivity if the system is overloading).

There was no special option needed to filter the signal from the detector for our measurement. During the data taking, the sensitivity and time constant were the most important parameters which could dictate the data quality. The sensitivity must be set not to overload the system. The time constant dictated how fast the RC circuit of the output channel discharges which would control

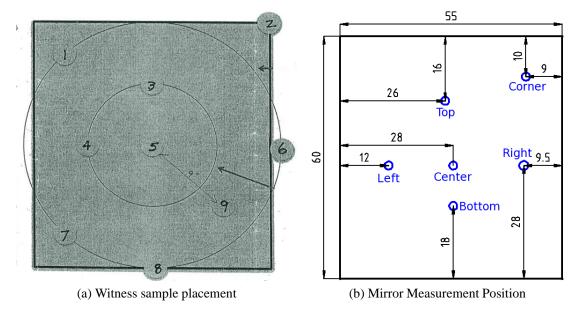


Figure 4: (a) Witness sample locations with respect to the main mirror position in the ECI aluminzation. (b) Reflectivity measurement locations on Mirror #8.

signal registration. A shorter time constant would allow a faster response to the signal change but larger fluctuation in signal strength, and a longer time constant would register stable signal strength but take longer to react to the any change in signal. The preferred time constant settings during the measurement were 1s and 3s.

For the data taking, monochromator was configured to perform a wavelength scan from 190-400nm at 5nm steps. The dwell time at each wavelength was 20s, and the associated time constant was 1s or 3s to generate a flat signal output. If the dwell time was 60s, the recommended time constant would be 3s or 10s (the time constant does not need to be larger than 10s).

A baseline (background) measurement should be taken before any real measurement. The monochromator light was diverted away from the detector so that only the background light falling into the chopping frequency window could be registered. The baseline (background) signal was measured to be  $1.6\times10^{-5}\mathrm{V}$  consistently, and  $R_{offset}$  was set for this value during all reflectivity measurements.

The signal magnitude R can be can be calculated as

$$R = \sqrt{(x + x_{offset})^2 + (y + y_{offset})^2} + R_{offset}$$
(3)

Where X and Y are the lock-in amplifier outputs in X, Y display mode[3].

### 2.6 Remarks During Data Taking

Although the large background noise can be filtered by the lock-in technique, sudden changes of the background during the measurement create large fluctuations in the signal output. Such sudden changes include switching on and off the room lights, a door opening, changing the view of the computer monitor, etc. It is important to create the constant background noise during the data taking process. The main room light and the computer monitors should be switched off and one should remotely control the system through the computer located in other userlab.

### 3 Results

### 3.1 Deuterium UV Lamp Thermal Test Results

The 3 Watt Hamamatsu deuterium UV source's stability has been questioned from the beginning. It was purchased 20 years ago by the FFL Facility at Jefferson Lab. A thermal effect test was carried out to investigate the stability of the UV lamp for long operation at the room temperature. The monochromator was set for 225nm wavelength, corresponding to a maximum signal output of 0.25mV. No Reflection (NR) mode was used for the test, where the light from monochromator was directly focused onto the detector by the focusing lens. The X and Y output from the lock-in amplifier were monitored separately as shown in Fig. 5.

After 6 hours of operation, we observed no fluctuation in either X or Y signal output, therefore signal magnitude R was also constant according to Eq. 3. From this result, we can safely conclude the UV source performance did not change due to heat and long operation, even without any method of cooling and ozone removal. Under the real testing scenario, the light source box will be

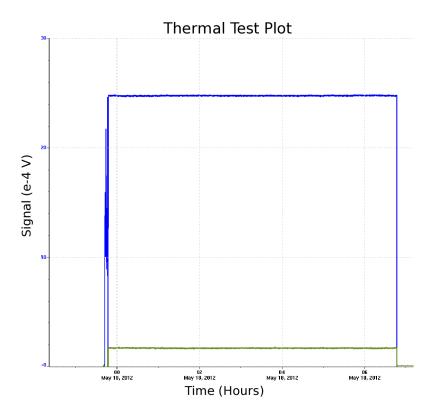


Figure 5: Lock-in amplifier X, Y signal strength monitoring of the Deuterium lamp for 6 hour testing period. The blue curve is the X signal and green curve is the Y signal.

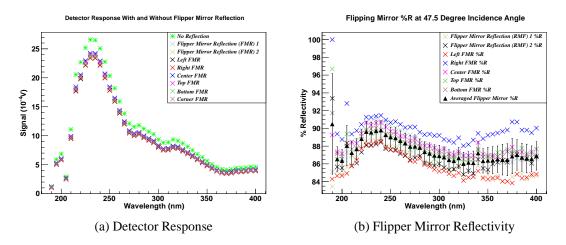


Figure 6: Flipper mirror reflectivity results. (a) shows the detector response; (b) shows the percentage reflectivity results.

constantly purged with cold  $N_2$  vapour, thus the UV source intensity should be stable during the long data taking process.

### 3.2 Flipper Mirror Reflectivity Result

In Fig. 6, 1 measurement of NR mode and 8 measurements of FMR mode wavelength scan curves are plotted. Measurements FMR1 and FMR2 were taken immediately after the NR measurement. The other 6 FMR measurements were taken separately within 6 hour period. The ratio between each of the FMR curve and NR curve is plotted in Fig. 6b. The averaged reflectivity curve and the standard deviation (error bar) are calculated and plotted. The standard deviation of percentage reflectivity at most of measured wavelength is between 1-2%, excepting at 190nm, where the signal is too close to the baseline to be trusted.

Between 220-400nm, the averaged reflectivity gradually increases as the wavelength goes deeper into the UV region, peaks around 235nm at 89.5%, and then starts to decease. At 200nm the reflectivity is 86.5%. The measured curve is different from the typical reflectivity curve for the Melles Griots DUV mirrors, see App. B. The typical curve peaks around 197nm at 94.5%, and gradually decreases as the wavelength increases. At 250nm the reflectivity is 91%. The difference between the measured and typical reflectivity curve is around 3% between 220-250nm; this difference will keep increasing as wavelength gets shorter and at 200nm region there is 8% difference.

There are a few possibilities that could contribute to the discrepancy between measured and

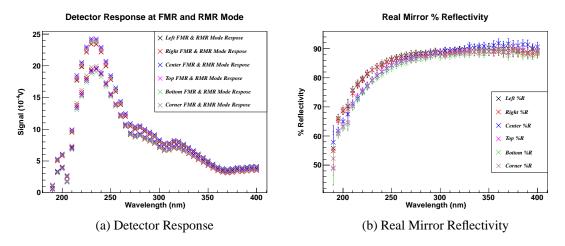


Figure 7: Real mirror reflectivity results

typical reflectivity curves, the typical curve is not a real measurement for the actual DUV mirror so some variation between the mirror performance and specification are expected. Also the mirror surface was scratched during the alignment process and the scratches would result in some scattered light.

### 3.3 HGC Mirror #8 Reflectivity Results

Fig. 7a shows 6 sets of FMR and RMR detector response curves. Each set of FMR and RMR measurements were taken after the mirror was adjusted to a new position for testing. For FMR measurements, the signal output was unrelated to the mirror position because the light was only reflected from the flipper mirror. For the RMR measurements the lens and flipper mirror positions needed to be adjusted, so light could reflect of the flipper mirror and real mirror. The FMR and RMR measurements were taken back to back, also the lens and flipper mirror positions were adjusted remotely, so that the testing environment was not disturbed. The orientation of the measured position (Left FMR, Right FMR and so on) on the mirror are demonstrated in the Fig. 4b.

Fig. 7b shows the reflectivity curves, which are the ratios between FMR and RMR measurements of the same orientation, for example (Left FMR curve)/(Left RMR curve). The plotted error bars were the same as for the averaged flipper mirror reflectivity. From the results, between 200-300nm, the reflectivity at the Center is worse than at the Corner; between 300-400nm, the reflectivity at the center is marginally better than at the corners.

During the aluminization process, ECI placed nine 1" witness samples at different locations across the test mirror as shown in Fig. 4a. The samples' reflectivity were tested for product quality

### Real Mirror Reflectivity - ECI Testing Sample Reflectivity

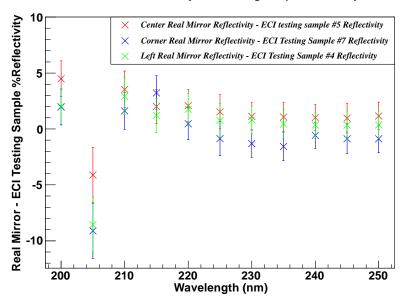


Figure 8: The difference between the witness samples and real measurement reflectivity results.

control, and these measurements are attached in App. C.

Witness sample reflectivity curves #4, #5 and #7 were chosen to compare with the measured reflectivity curves at positions Left, Center and Corner between 200-250nm wavelength. The mirror testing positions of #4 and Left, #5 and Center, #7 and Corner are similar. The sample reflectivity curves were subtracted from the measured reflectivity curve and the difference is plotted in Fig. 8. The ECI sample results have significant jitter. The estimated error below 230nm is 1% and above 230nm is 0.5%. The error bar in Fig. 8 is calculated by

$$\delta_{Difference} = \sqrt{\delta_{ECI}^2 + \delta_{Measurement}^2} \tag{4}$$

where  $\delta_{ECI}$  is the ECI sample result error and  $\delta_{Measurement}$  is the measurement error. For most of the points, the difference is between 0-3%, which means the measured percentage reflectivity is higher than the witness sample reflectivity. At the corner, the differences are slightly below 0, but 0 is still within the error bar. In the ECI witness sample results there is a sharp peak at 205nm which does not exist in our measurement. Despite the peak, we can confirm the ECI sample testing result represents the performance of the product and success of the reflectivity measurement setup.

### 3.4 Uncertainty

The UV detector response uniformity was tested with a smaller focused beam of  $6\text{mm} \times 4\text{mm}$  at 225nm. Five measurements were taken: one at the center and four at the corners with 1mm clearance to the edge. The response signal differences were around 1-2%. For the real mirror measurement alignment, the focused spot was not guaranteed to be at the same location. The uniformity error should have already been included into the reproducibility error, which was computed by 8 measurements of FMR Mode. The reproducibility error should be representative for the real mirror reflectivity.

### 4 Conclusion

Based upon the real HGC mirror reflectivity measurements, we can safely confirm the ECI witness sample measurement represents the reflectivity performance of the aluminized mirror surface between 200-400nm. At 200nm wavelength, the reflectivity is 10% lower than the original ECI claimed value of 76% with the worst witness sample results. However, this difference decreases rapidly as the wavelength increases. At 250nm, the difference between the sample curves and theoretical curves ranges between 0-5%. Based on the Geant4 simulation results, the difference between the theoretical curve and worst sample curve corresponds to 2.5% in terms of the detected photo-electrons and 0.13% in terms of detected pion events. This effect is insignificant compared to other significant contributions to the UV absorption in the deep UV region, i.e the C<sub>4</sub>F<sub>8</sub>O gas absorption etc. We believe ECI product quality meets specified performance and is sufficient for the real HGC mirror aluminization.

We are also delighted to report that the reflectivity setup at Jefferson Lab is capable of measuring the large size optics reflectivity between 200-400nm wavelength at normal atmospheric condition and is potentially able to measure the reflectivity down to 165nm wavelength under the  $N_2$  purged environment.

### 5 Suggestions for the Future Measurement

It is not obvious if the current UV source is suitable for UV measurements below 190nm. Further testing is required to confirm that the signal strength is sufficiently strong and stable at such low wavelength. One of the possible options is to replace the 3Watt Hamamastu deuterium lamp with a Newport Oriel 30Watt deuterium lamp, which has much higher intensity at lower wavelength.

At the moment, the setup is in a semiautomatic state, where some manual fine adjustments are required. Also, the cameras which can help with the alignment and status check are yet to be installed. For the Noble Gas Čerenkov mirror reflectivity measurements, the detector hutch enclosure with pure  $N_2$  environment will forbid any manual adjustment and alignment. Some level of automation is needed. However, it is not obvious at the moment how accurate automatic alignment can be achieved. Manpower needs to be committed to resolve this issue.

# References

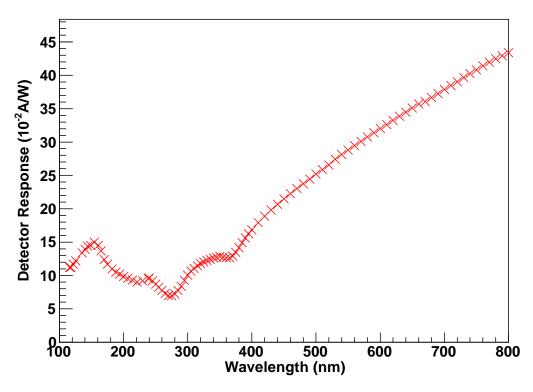
- [1] W. Li, G. Huber, M. Denissenya, D. Gervais, L. Sichello, K. Wolbaum, *Mirror Testing Result*, Hall C Document 716-v1, 2011.
- $[2] \ http://www.ird-inc.com/text/SXUV\%20RESPONSIVITY\%20MASTER.txt$
- [3] SR530 Lock-in Amplifier User Manual.

# **Appendix**

# **A AXUV-100G Detector Response Curve**

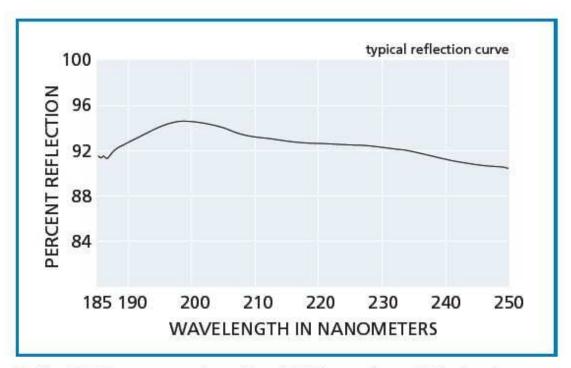
The graph below shows the signal response curve for the IRD AXUV-100G detector between 100-800nm. The numerical data are provided by the IRD company[2].

### **Detector Response**



# **B** Typical Melles Griots DUV Mirror Reflectivity Curve

The graph below shows the typical Melles Griots DUV mirror reflectivity between 185-250nm wavelength.



Reflectivity vs wavelength of 193 nm deep UV aluminum coating at 45°

# **C** ECI Testing Sample Reflectivity Measurements

The ECI data sheets are attached in the following three pages, the actual placement of the witness samples with respect to the real mirror are shown in Fig. 4a. The first page of the data sheet is the theoretical reflectivity performance; 2nd and 3rd page are the reflectivity measurement of the witness samples.



# **Coating Spectral Performance**

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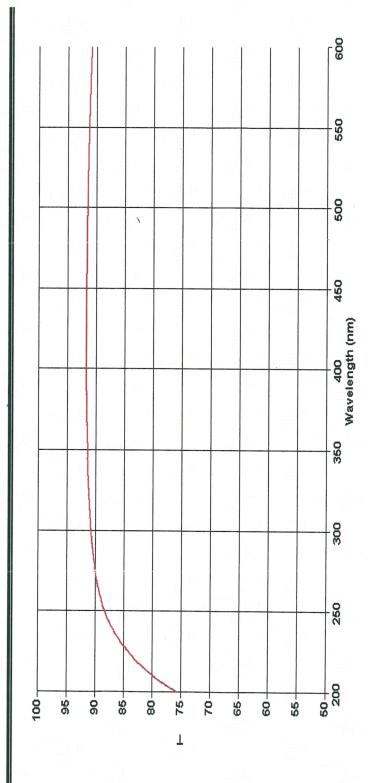
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Run #: 1-65

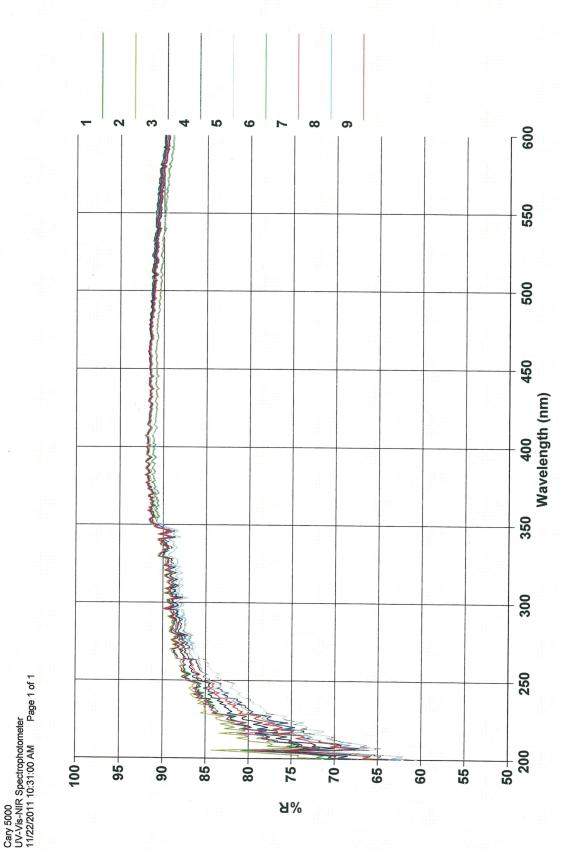
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Analyst: KH

Remarks: HGC Mirror

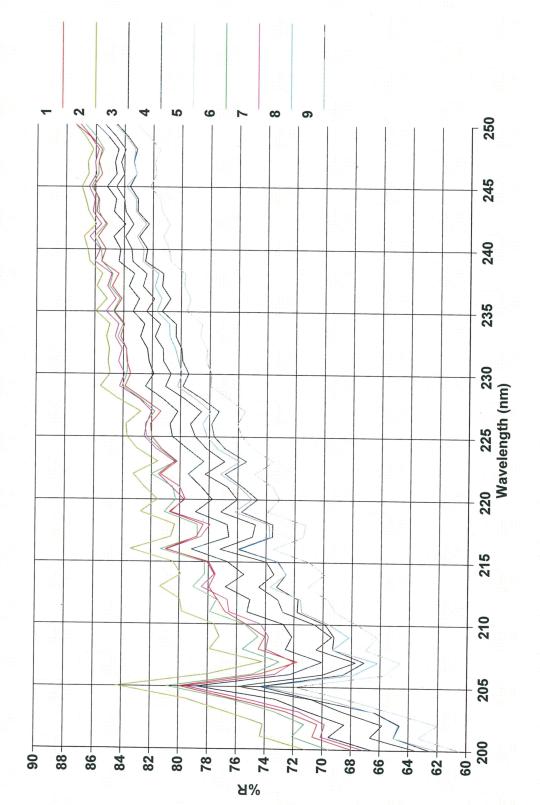


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